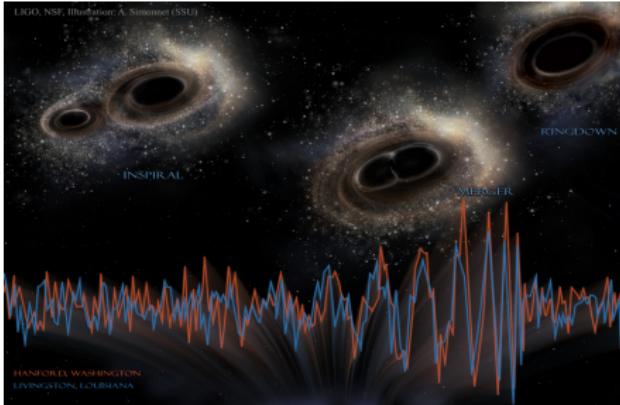


# Listening to Ripples in Space-Time: Cosmological Inference from Standard Sirens

Jacob Tutt<sup>1</sup>

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# New Era of GW Detection



Credit: A. Simonnet (Sonoma State)

## Scientific Opportunities

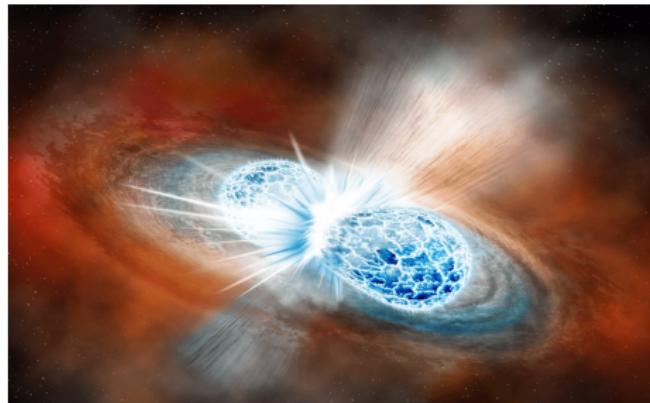
- ▶ Probe extreme matter and fields
- ▶ Enable multi-messenger astronomy (GW170817 - 2017)
- ▶ 'Standard sirens' allow construction of distance ladder

## Gravitational Wave Detections

1916: Einstein's  
Theoretical Prediction

2025: Over 290 GW  
Events Detected

2015: First Observational  
Detection – GW150914



Credit: NASA

# Statistical Detection of GWs

## Goal:

- ▶ Implementation of some of the key statistical approaches used for GW detection and localisation.
- ▶ **Approach:**
  - ▶ ‘Match Filtering’ for:
    - ▶ Signal identification
    - ▶ Sky Triangulation
  - ▶ A Bayesian approach to GW analysis:
    - ▶ Sky Localisation, RA and Dec
    - ▶ Luminosity Distance,  $D_L$
  - ▶ Cosmological Inference of Hubble’s Constant,  $H_0$

# Interferometer Data

## Strain and Space-Time Distortion

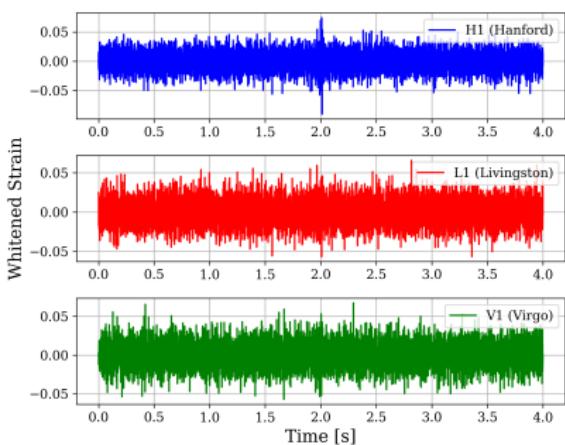
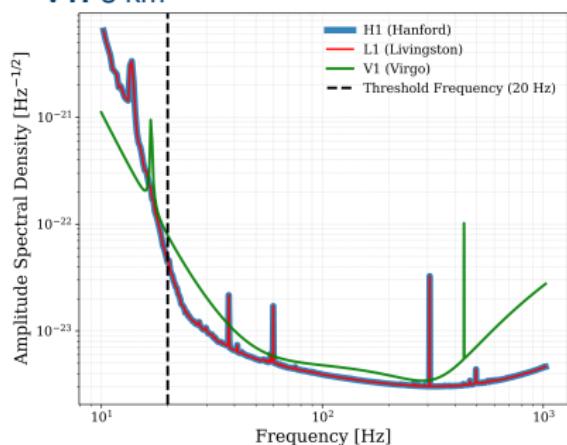
$$h(t) = \frac{\Delta L(t)}{L}$$

## Power Spectral Density (PSD)

$$\langle \tilde{n}(f)\tilde{n}^*(f') \rangle = \frac{1}{2} S_n(f)\delta(f - f')$$

### Interferometer Arm Lengths, $L$ :

- ▶ H1 and L1: 4 km
- ▶ V1: 3 km



# Antenna Response Functions

## Antenna Sensitivity:

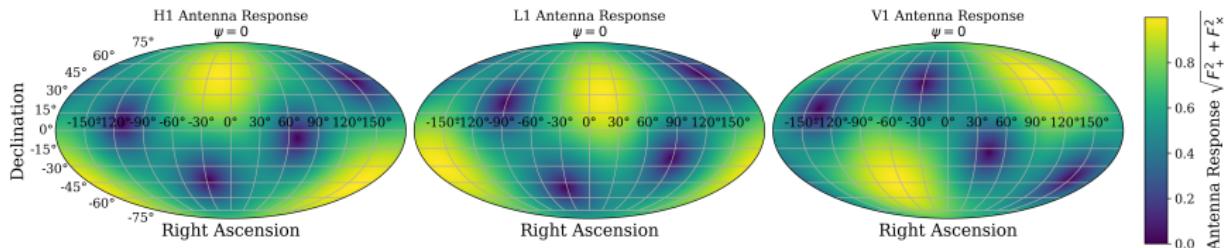
Orientation (3D) of the detector relative to the quadrupolar distortion:

$$\tilde{h}_{\text{det}}(f) = F_+ \tilde{h}_+(f) + F_\times \tilde{h}_\times(f)$$

Where  $F_+$  and  $F_\times$  depend on:

- ▶ Right ascension and declination
- ▶ Polarisation angle  $\Psi$
- ▶ GPS Time  $t_{\text{GPS}}$

## Geography of Interferometers:



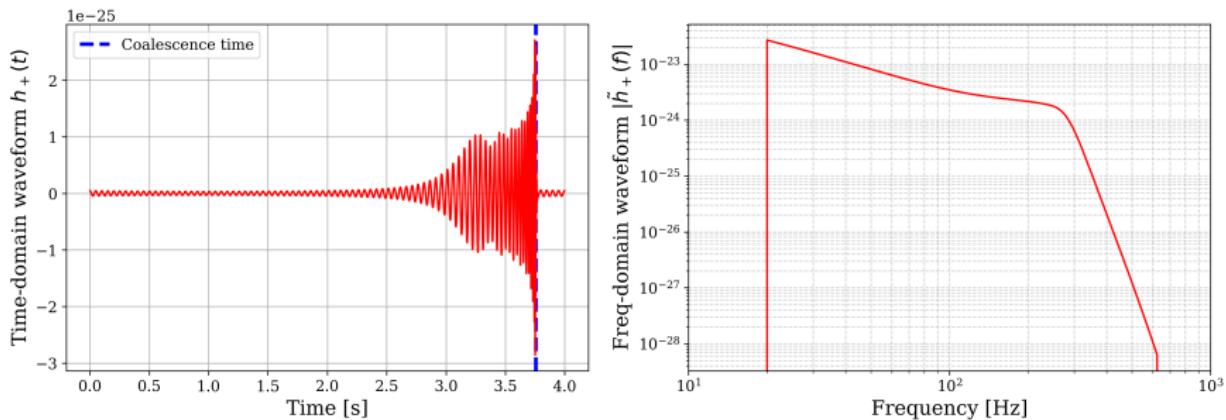
# Waveform Models

## Waveform + Detection Parameters:

$$\theta_{\text{BBH}} = \{m_1, m_2, \vec{S}_1, \vec{S}_2, D_L, \alpha, \delta, \iota, \psi, t_c, \phi_c\} \quad (1)$$

## Detection Parameters:

$$\theta_{\text{Red}} = \{D_L, \alpha, \delta, \psi, t_c\} \quad (2)$$



# Match Filtering: Mathematical Derivation

A given ‘optimal filter’,  $K(t)$  and the interferometer’s detected signal:  $s(t) = n(t) + h(t)$  - cross correlation leads to:

$$\rho_{\text{mf}}^2(t_c) = \frac{S^2}{N^2} = (S * K)(t_c) = \int_{-\infty}^{\infty} dt S(t)K(t - t_c) \quad (3)$$

---

Parseval Theorem:  $\int_{-\infty}^{\infty} dt S(t)K^*(t) = \int_{-\infty}^{\infty} df \tilde{S}(f)\tilde{K}^*(f)$

$$(4)$$

Fourier Translation:  $\mathcal{F}[K(t-t_c)](f) = \tilde{K}(f)e^{-2\pi ift_c}$

$$(5)$$

Overall:  $\rho_{\text{mf}}^2(t_c) = \int_{-\infty}^{\infty} df \tilde{S}(f)\tilde{K}^*(f)e^{2\pi ift_c}$

$$(6)$$

# Match Filtering: Mathematical Derivation

$$\rho_{\text{mf}}^2(t_c) = \int_{-\infty}^{\infty} df \tilde{S}(f) \tilde{K}^*(f) e^{2\pi i f t_c} \quad (7)$$

---

Optimal Filter (Cauchy Schwarz):  $\tilde{K}(f) = \frac{\tilde{h}(f)}{S_n(f)}$

$$(8)$$

Real Valued Time Series:  $\rho_{\text{mf}}^2(t_c) = 4\Re \int_0^{\infty} df \frac{\tilde{s}(f)\tilde{h}^*(f)}{S_n(f)} e^{2\pi i f t_c}$

$$(9)$$

Inverse Fourier Tranform:  $\rho_{\text{mf}}^2(t_c) = 4\Re \mathcal{F}^{-1} \left[ \frac{\tilde{s}(f)\tilde{h}^*(f)}{S_n(f)} \right] (t_c)$

$$(10)$$

# Matched Filtering: Implementation

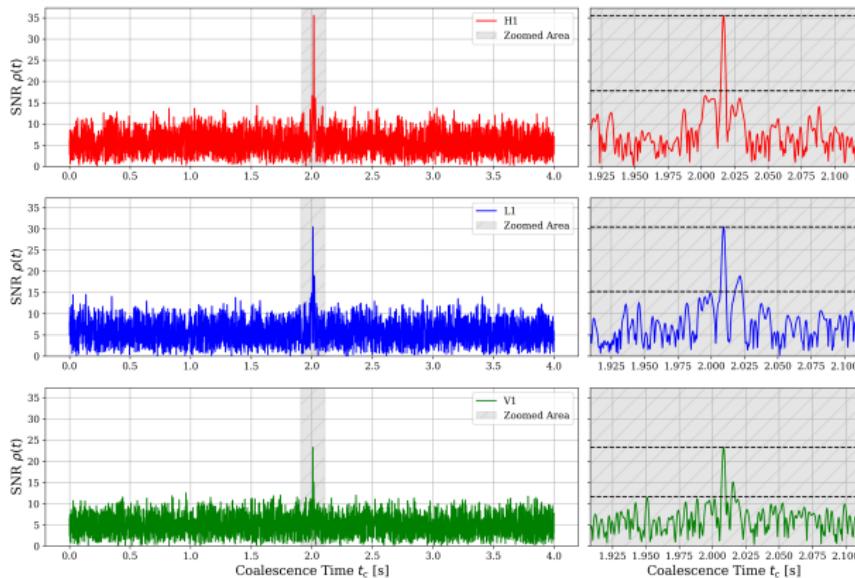
## Filter Optimisation:

- ▶ GW waveform fixed, but detector response varies
- ▶ Depends on antenna patterns  $F_+, F_\times(\text{RA}, \text{Dec}, \psi, t_{\text{GPS}})$
- ▶ Filter bank: mesh grid over RA, Dec,  $\psi$
- ▶ Maximise SNR for each detector

Detector	$\sigma_{\text{SNR}}$	$\sigma_{t_c} (\text{s})$	RA (rad)	Dec (rad)	$\psi$ (rad)
Hanford (H1)	5.329	0.001	0.381	0.796	1.988
Livingston (L1)	4.563	0.001	3.998	-0.535	2.885
Virgo (V1)	3.491	0.001	5.775	-0.739	2.372

Table: Standard deviations of SNR and  $t_c$  across grid of RA, Dec, and  $\psi$ , with parameters that maximise the SNR for each detector.

# Matched Filtering: Results



	<b>SNR</b>	<b>Time (s)</b>
H1	35.52	$2.017 \pm 0.002$
L1	30.48	$2.009 \pm 0.002$
V1	23.28	$2.008 \pm 0.002$

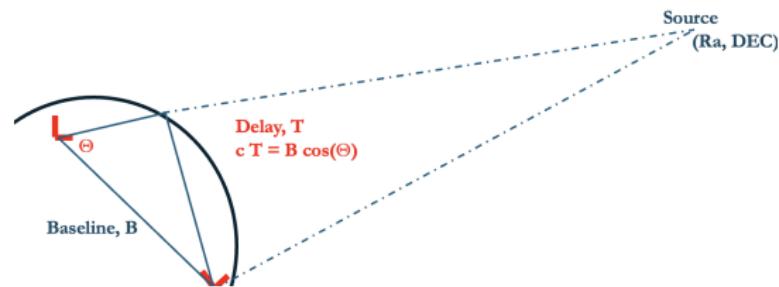
# Sky Triangulation: Theory

For a given  $\alpha, \delta$  - 'true' time-delays from geocenters combined:

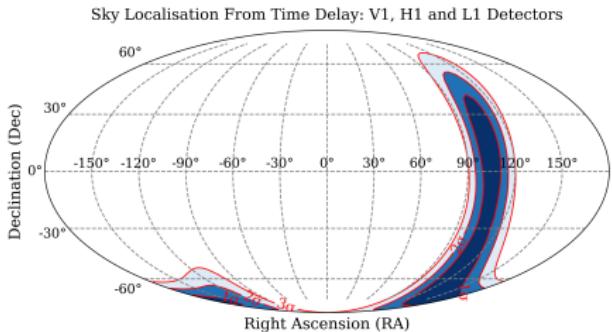
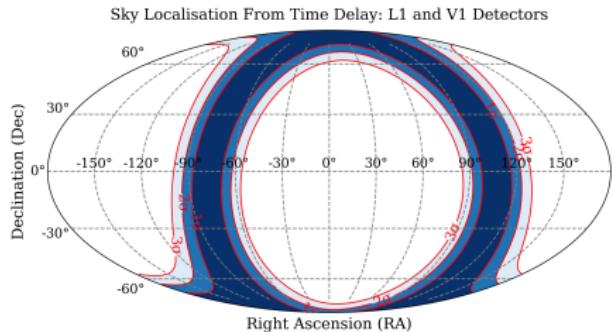
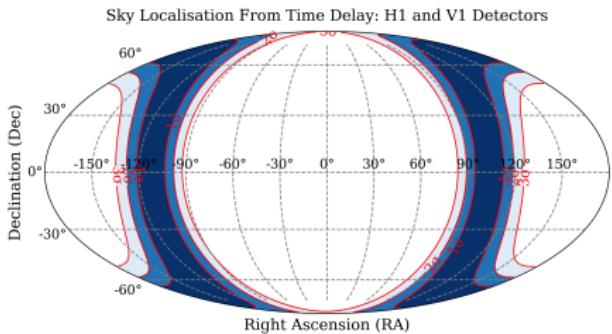
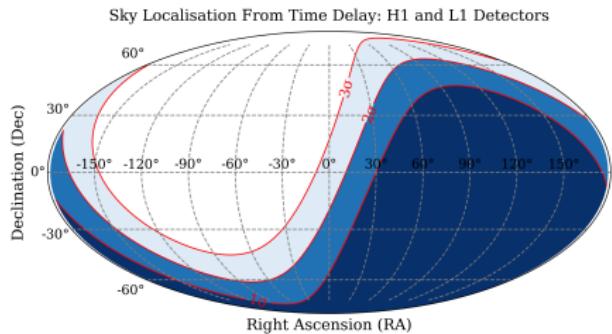
$$\Delta t_{1,2}^{\text{true}}(\alpha, \delta) = \tau_1(\alpha, \delta) - \tau_2(\alpha, \delta). \quad (11)$$

For N baselines - Gaussian Likelihood Model:

$$\log \mathcal{L}(\alpha, \delta) \propto -\frac{1}{2} \sum_{i < j} \left( \frac{\Delta t_{i,j}^{\text{obs}} - \Delta t_{i,j}^{\text{true}}(\alpha, \delta)}{\sigma_{i,j}} \right)^2 \quad (12)$$



# Sky Triangulation: Results



# Sky Triangulation: Results

## Areas of Confidence Intervals:

Detectors	$1\sigma$ % Sky	$2\sigma$ % Sky	$3\sigma$ % Sky
H1 - L1	38.0	50.7	64.2
H1 - V1	17.3	29.7	43.8
L1 - V1	23.9	38.4	51.8
H1 - L1 - V1	3.9	9.1	15.4

## Comparison of Baselines' Lengths:

Detector Pair	Time Delay (ms)	Total Light Travel Time (ms)
H1 - L1	$7 \pm 3$	10
H1 - V1	$8 \pm 3$	27
L1 - V1	$0.1 \pm 3.0$	26

# Bayesian Analysis for GW Waves:

## Formulation of Likelihood (Noise Only):

For stationary - Gaussian Noise:

$$\mathcal{L}(n \mid H_{\text{noise}}) = \prod_{i=0}^N \mathcal{L}(\tilde{n}(f_i) \mid H_{\text{noise}}) = \mathcal{N} \exp \left( -\frac{(n|n)}{2} \right) \quad (13)$$

Inner product is defined using the PSD  $S_n(f)$ :

$$(a|b) = 4 \Re \left[ \int_0^\infty df \frac{\tilde{a}(f)\tilde{b}^*(f)}{S_n(f)} \right] = 4 \Delta f \Re \left[ \sum_{i=0}^{N_f-1} \frac{\tilde{a}(f)\tilde{b}^*(f)}{S_n(f)} \right] \quad (14)$$

# Bayesian Analysis for GW Waves:

## Formulation of Likelihood (Signal):

For a given signal with a detector response  $h_{\vec{\theta}}(t)$ :

$$\mathcal{L}(d, \vec{\theta}) = \mathcal{P}(d | \vec{\theta}, H_{\text{signal}}) = \mathcal{P}(d - h_{\vec{\theta}} | H_{\text{noise}}) \quad (15)$$

$$\mathcal{L}(d, \vec{\theta}) = \mathcal{N} \exp \left( -\frac{\langle d - h_{\vec{\theta}} | d - h_{\vec{\theta}} \rangle}{2} \right) \quad (16)$$

$$\log \mathcal{L}(d | \vec{\theta}) \propto -2 \Delta f \sum_{i=0}^{N_f-1} \frac{|\tilde{d}(f_i) - \tilde{h}_{\vec{\theta}}(f_i)|^2}{S_n(f_i)} \quad (17)$$

# Bayesian Analysis for GW Waves:

## Formulation of Multi Detector Likelihood:

For multiple detectors,  $\{d_{\mathcal{I}}\}_{\mathcal{I}=1}^{N_{\text{det}}}$ :

$$\mathcal{P}(\{d_{\mathcal{I}}\} \mid \vec{\theta}) = \prod_{\mathcal{I}} \mathcal{P}(d_{\mathcal{I}} \mid \vec{\theta}) \propto \exp \left( - \sum_{\mathcal{I}} \frac{\langle d_{\mathcal{I}} - h_{\vec{\theta}} \mid d_{\mathcal{I}} - h_{\vec{\theta}} \rangle}{2} \right) \quad (18)$$

$$\log \mathcal{L}(\{d_{\mathcal{I}}\} \mid \vec{\theta}) \propto -2\Delta f \sum_{\mathcal{I}=1}^{N_{\text{det}}} \sum_{i=0}^{N_f-1} \frac{|\tilde{d}_{\mathcal{I}}(f_i) - \tilde{h}_{\vec{\theta}, \mathcal{I}}(f_i)|^2}{S_n^{(\mathcal{I})}(f_i)} \quad (19)$$

# Adjusting Waveform Model

## 1. Antenna Response: Adjust for Sky Position

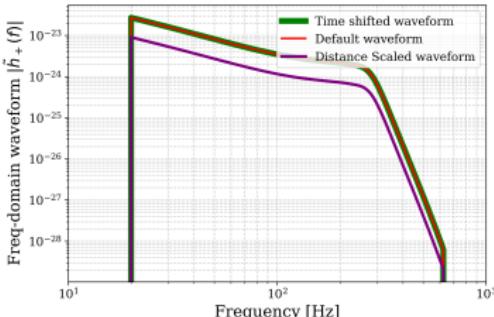
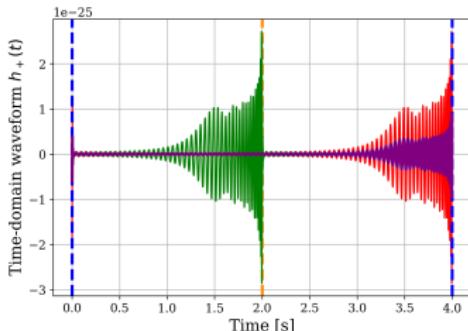
$$\tilde{h}_{\text{det}}(f) = F_+(RA, Dec, \psi) \tilde{h}_+(f) + F_\times(RA, Dec, \psi) \tilde{h}_\times(f)$$

## 2. Fourier Shift: Shift to Geocentric Coalescence Time

$$t_c^{\text{det}} = t_c^{\text{geo}} + \Delta t_{\text{delay}}(RA, Dec) \Rightarrow h_{\text{det}}(t_c^{\text{geo}}) \xrightarrow{\mathcal{F}} \tilde{h}_{\text{det}}(f) e^{2\pi i f t_c^{\text{det}}}$$

## 3. Scaling: Adjust for Luminosity Distance

$$\tilde{h}_{\text{det}}(f; D_L) = \left( \frac{1 \text{ Gpc}}{D_L} \right) \tilde{h}_{\text{det}}(f)$$

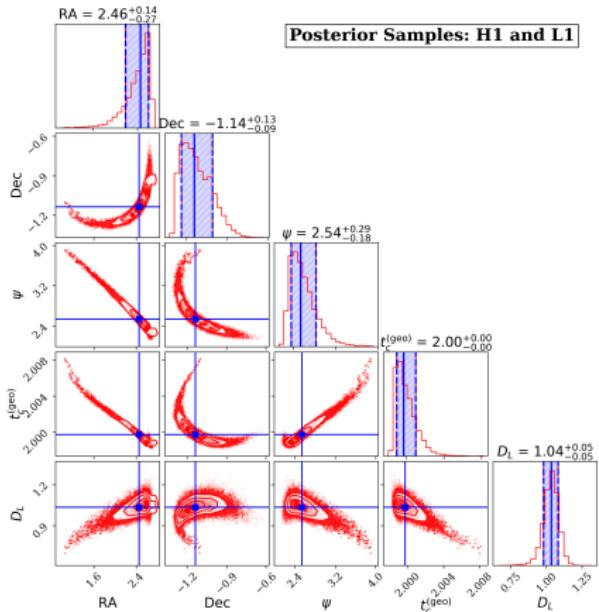


# Prior Distributions

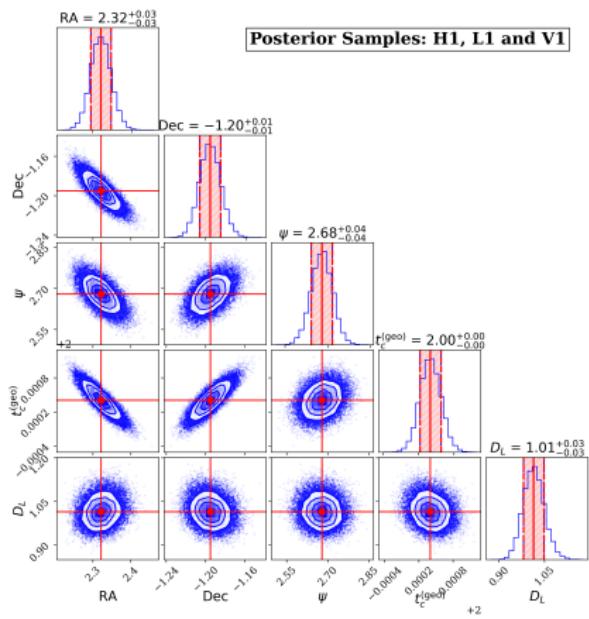
Parameter	Prior Description
RA	Uniform over $[0, 2\pi]$
Dec	Uniform in solid angle: $\sin(\text{Dec}) \in [-1, 1]$
$\psi$	Uniform over $[0, \pi]$
$t_{\text{geo}}^c$	Uniform over $[0, 4]$ seconds
$D_I$	Log-uniform over $[10^{-2}, 100]$ Gpc (i.e. 10 Mpc to 100 Gpc)

# Nested Sampling

## Likelihood: H1 and L1

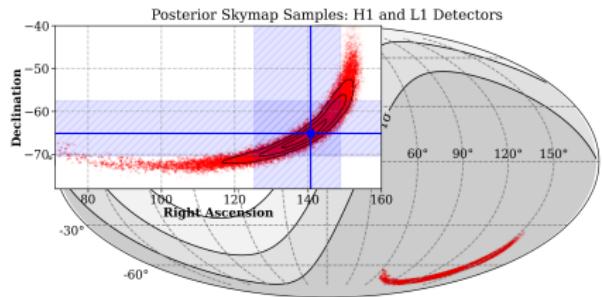


## Likelihood: H1, L1 and V1

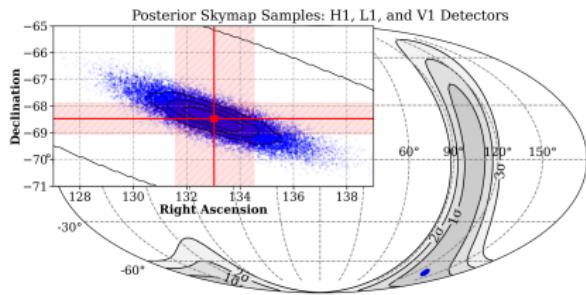


# Sky Map Distributions

## Skymap: H1 and L1



## Skymap: H1, L1 and V1



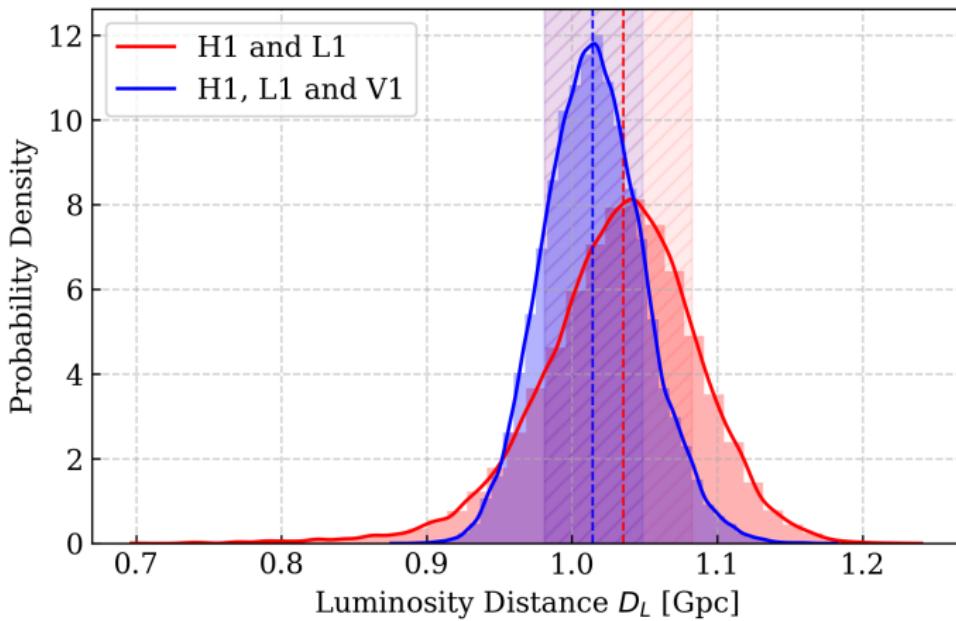
### Posterior Localisation:

Detectors	1 $\sigma$ % Sky	2 $\sigma$ % Sky	3 $\sigma$ % Sky
H1 - L1	0.15	0.41	0.81
H1 - L1 - V1	0.00	0.01	0.02

### Triangulation Localisation (for context):

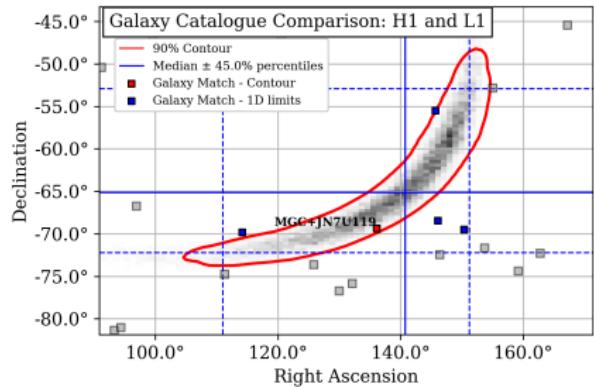
Detectors	1 $\sigma$ % Sky	2 $\sigma$ % Sky	3 $\sigma$ % Sky
H1 - L1	38.0	50.7	64.2
H1 - L1 - V1	3.9	9.1	15.4

# Luminosity Distance, $D_L$

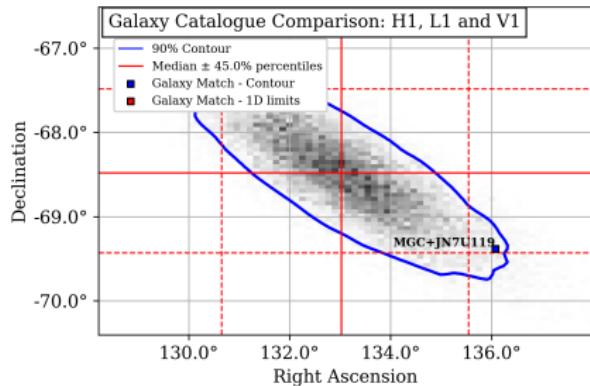


# Host Galaxy Identification

## Posterior: H1 and L1



## Posterior: H1, L1 and V1



Name	RA	Dec	Redshift, z
MGC+JN7U119	2.375	-1.211	0.226

# Cosmological Inference: Theory

**Hubble Constant,  $H_0$  ( $Z \ll 1$ ):**

$$H_0 = \frac{c \cdot z}{D_L} \quad (20)$$

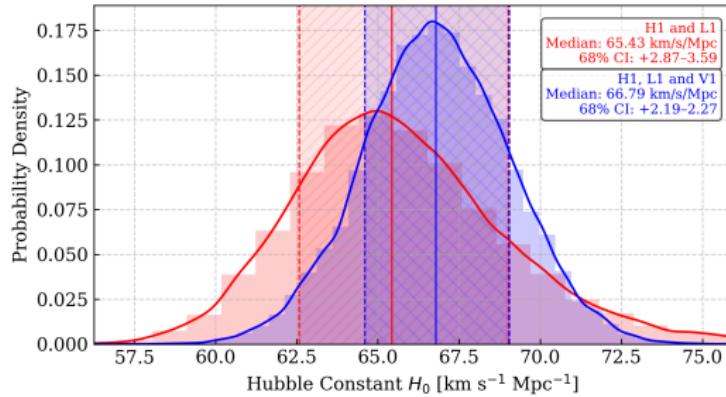
**Caveated:**

$$D_L = (1 + z) S_k[r_{CM}] \quad r_{CM} = c \int_0^z \frac{1}{H(z')} dz' \quad (21)$$

$$D_L \approx \frac{c}{H_0} \left[ z + \frac{1}{2}(1 - q_0)z^2 + \dots \right], \quad q_0 = \frac{1}{2}\Omega_{M,0} - \Omega_{\Lambda,0} \quad (22)$$

# Hubble Constant

## Posterior Distributions:



## Hubble Tension:

---

Method	$H_0$ [km/s/Mpc]
Distance ladder (Milky Way Cepheids)	$73.2 \pm 1.3$
H0LiCOW Gravitational lensing	$73.3 \pm 1.7$
Planck CMB	$67.4 \pm 0.5$

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# Questions

**Thank you for your attention!**  
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